

일반물리 Chapter. 11

15

$$\vec{r} = 3m\hat{i} + 1m\hat{j}$$

$$\begin{aligned} \text{(a)} \quad \vec{r} \times \vec{F} &= (3m\hat{i} + 1m\hat{j}) \times (12N\hat{i}) \\ &= 36N \cdot m (\hat{i} \times \hat{i}) + 12N \cdot m (\hat{j} \times \hat{i}) \\ &= \underline{12N \cdot m (-\hat{k})} \end{aligned}$$

$$\begin{aligned} \text{(b)} \quad \vec{r} \times \vec{F} &= (3m\hat{i} + 1m\hat{j}) \times (12N\hat{j}) \\ &= 36N \cdot m (\hat{i} \times \hat{j}) + 12N \cdot m (\hat{j} \times \hat{j}) \\ &= \underline{36N \cdot m \hat{k}} \end{aligned}$$

$$\begin{aligned} \text{(c)} \quad \vec{r} \times \vec{F} &= (3m\hat{i} + 1m\hat{j}) \times 12N\hat{k} \\ &= 36N \cdot m (\hat{i} \times \hat{k}) + 12N \cdot m (\hat{j} \times \hat{k}) \\ &= \underline{36N \cdot m (-\hat{j}) + 12N \cdot m \hat{i}} \end{aligned}$$

18.

$$(a). \vec{L} = \int \vec{c} dt, \quad \vec{c} = \vec{r} \times \vec{F}, \quad \vec{F} = m\vec{a}$$

$$(kg)(m/s^2)(m)(s) = \boxed{kg \cdot m^2/s}$$

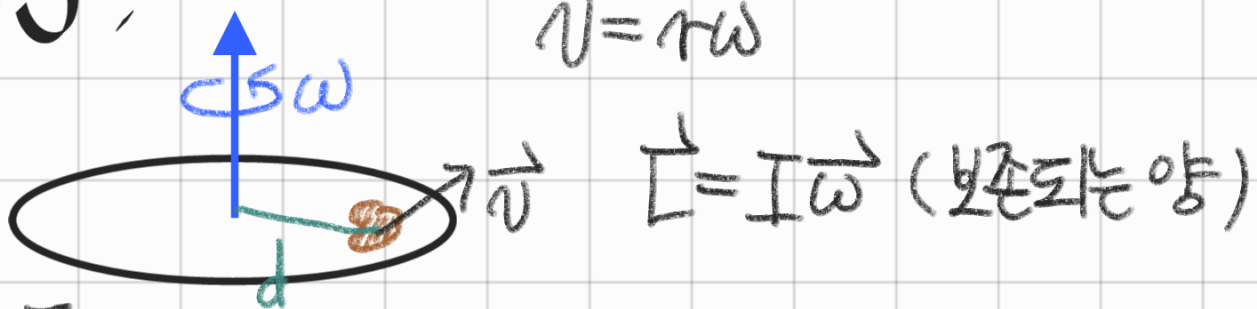
(b).

$$(N)(m)(s) = \boxed{N \cdot m \cdot s}$$

(c).

$$(J)(s) = \boxed{J \cdot s}$$

55.



처음 각속력을 ω_i , 나중에 각속력을 ω_f

$$(a) I_{tot} = I + md^2$$

$$\begin{aligned} \vec{L} &= I_{tot} \vec{\omega} = (I + md^2) \omega_i = (I + md^2) \omega_f \\ &= I\omega + mvd = (I + md^2) \omega_f \end{aligned}$$

$$mvd = I(\omega_f - \omega) + md^2\omega_f$$

$$v = \frac{I}{mvd}(\omega_f - \omega) + d\omega_f$$

$$v = \frac{I}{m_d} \cdot -\frac{1}{2}\omega + d\frac{1}{2}\omega$$

$$\therefore v = \frac{1}{2}\omega \left(d - \frac{I}{m_d} \right)$$

$$(b). \quad v = \frac{I}{m_d} \cdot 0 + d\omega$$

$$\therefore v = d\omega$$

$$(c). \quad v = \frac{I}{m_d} \omega + 2d\omega$$

$$\therefore v = 2\omega \left(1 + \frac{I}{2m_d} \right)$$

$$58. \vec{L} = I\vec{\omega}, \text{ 원판의 } I = \frac{1}{2}MR^2$$

$$L_i = \frac{1}{2}MR^2\omega_i, \quad L_f = \frac{1}{2}(MR^2 + mR^2)\omega_f$$

$$L = \frac{1}{2}MR^2\omega_i = \frac{1}{2}(MR^2 + mR^2)\omega_f$$

$$\frac{1}{2}(440g)(3.5cm)^2(180rpm)$$

$$= \frac{1}{2} \left\{ (440g)(3.5cm)^2 + (270g)(2.3cm)^2 \right\} \omega_f$$

$$\therefore \omega_f = \text{약 } 142.3 \text{ rpm} \quad (a)$$

$$\text{회전 운동에너지: } KE = \frac{1}{2}I\omega^2 = \frac{1}{2}\frac{L^2}{I}$$

$$\frac{KE_i - KE_f}{KE_i} \quad (\text{잃어버린 회전 KE의 비율})$$

$$= 1 - \frac{KE_f}{KE_i} = 1 - \left(\frac{\frac{1}{2}\frac{L_f}{I_f}}{\frac{1}{2}\frac{L_i}{I_i}} \right) = 1 - \frac{L_f I_i}{L_i I_f}$$

$$L_i = L_f \text{ 이므로}$$

$$1 - \frac{I_i}{I_f} = \text{약 } 0.21 \Rightarrow \text{약 } 21\% \quad (b)$$

59.

$$I_{\text{sphere}} = \frac{2}{5} MR^2, \quad \tau = -\mu_k MgR \text{ (구의 회전 방향에 반대)}$$

$$\tau = I\alpha = -\mu_k MgR \rightarrow \alpha = \frac{-\mu_k MgR}{\frac{2}{5} MR^2} = -\frac{5}{2} \frac{\mu_k g}{R}$$

(a). $\omega = \omega_0 + \alpha t$ 에 대입. $\omega = \omega_0 - \frac{5}{2} \frac{\mu_k g}{R} t$

$v = v_0 + at$ 를 이용하여 t 를 구하자.

$$f \text{ (마찰력)} = \mu_k Mg = Ma \rightarrow a = \mu_k g$$

⇒ **병진 운동은 가속이지만, 회전 운동은 방해**

$$v = v_0 + \mu_k g t, \quad \omega = \omega_0 - \frac{5}{2} \frac{\mu_k g}{R} t$$

초기 속력 $v_0 = 0$ 이므로, $v = \mu_k g t. \Rightarrow t = \frac{v}{\mu_k g}$

$$\omega = \omega_0 - \frac{5}{2} \frac{\mu_k g}{R} \cdot \frac{v}{\mu_k g}, \quad \text{그러나 } v = R\omega.$$

$$\omega = \omega_0 - \frac{5}{2} \omega \Rightarrow \boxed{\omega = \frac{2}{7} \omega_0}$$

(b). $t = \frac{v}{\mu_k g} = \frac{\omega R}{\mu_k g} = \boxed{\frac{2}{7} \frac{R\omega_0}{\mu_k g}}$